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Chapter 1 Introduction

Defense was the first application sector for augmented reality (AR) and virtual reality (VR), as far back as the 1950s. Based on such early developments, the first consumer AR/VR boom expanded in the early 1990s and contracted considerably throughout that decade, a poster child of a technology ahead of its time and also ahead of its markets.² However, due to the lack of available consumer display technologies and related sensors, novel optical display concepts were introduced throughout the 90s^{3,4} that are still considered as state of the art, such as the "Private Eye" smart glass from Reflection Technology (1989) and the "Virtual Boy" from Nintendo (1995)—both based on scanning displays rather than flat-panel displays. Although such display technologies were well ahead of their time, 5-7 the lack of consumergrade IMU sensors, low-power 3D-rendering GPUs, and wireless data transfer technologies contributed to the end of this first VR boom. The other reason was the lack of digital content, or rather the lack of a clear vision of adapted AR/VR content for enterprise or consumer spaces.^{8,9}

The only AR/VR sector that saw sustained efforts and developments throughout the next decade was the defense industry (flight simulation and training, helmet-mounted displays (HMDs) for rotary-wing aircrafts, and head-up displays (HUDs) for fixed-wing aircrafts). The only effective consumer efforts during the 2000s was in the field of automotive HUDs and personal binocular headset video players.

Today's engineers, exposed at an early age to ever-present flat-panel display technologies, tend to act as creatures of habit much more than their peers 20 years ago, who had to invent novel immersive display technologies from scratch. We have therefore seen since 2012 the initial implementations of immersive AR/VR HMDs based on readily available smartphone display panels (LTPS-LCD, IPS-LCD, AMOLED) and pico-projector micro-display panels (HTPS-LCD, mu-OLED, DLP, LCoS), IMUs, and camera and depth map sensors (structured light or time of flight (TOF)). Currently, HMD architectures are evolving slowly to more specific technologies, which might be a

better fit for immersive requirements than flat panels were, sometimes resembling the display technologies invented throughout the first AR/VR boom two decades earlier (inorganic mu-iLED panels, 1D scanned arrays, 2D laser/VCSEL MEMS scanners, etc.).

The smartphone technology ecosystem, including the associated display, connectivity, and sensor systems, shaped the emergence of the second AR/VR boom and formed the first building blocks used by early product integrators. Such traditional display technologies will serve as an initial catalyst for what is coming next.

The immersive display experience in AR/VR is, however, a paradigm shift from the traditional panel display experiences that have existed for more than half a century, going from CRT TVs, to LCD computer monitors and laptop screens, to OLED tablets and smartphones, to LCoS, DLP, and MEMS scanner digital projectors, to iLED smartwatches (see Fig. 1.1).

When flat-panel display technologies and architectures (smartphone or micro-display panels) are used to implement immersive near-to-eye (NTE) display devices, factors such as etendue, static focus, low contrast, and low brightness become severe limitations. Alternative display technologies are required to address the needs of NTE immersive displays to match the specifics of the human visual system.

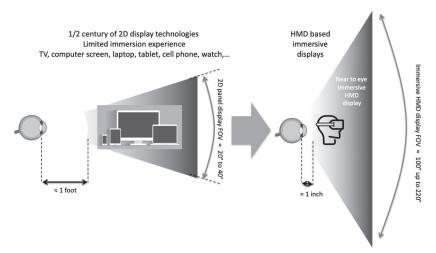


Figure 1.1 Immersive NTE displays: a paradigm shift in personal information display.

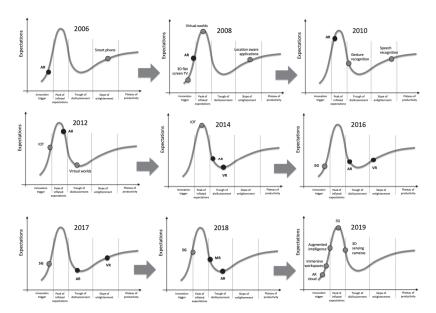


Figure 2.1 Gartner Hype Cycles for Emerging Technologies (2006–2019) for AR/VR/MR.

The 2008–2010 span introduced several technologies to the cycle that are now critical pillars to the AR experience, such as location-aware applications, gesture recognition, and speech recognition. Gesture recognition has had a tremendous boost with the Kinect technology development for the Xbox through 2009–2015 (structured illumination and then TOF), as well as speech recognition for personal assistants in smartphones.

IOT technologies appeared on the graph in 2012, culminated in hype in 2014, and were dropped promptly the next year, becoming a real product used by millions in consumer and enterprise fields. Many IOT core technologies share functionality with AR hardware.

AR peaked in its hype from 2010–2012, the years when Google Glass was introduced, along with many other smart glasses (Lumus, Optinvent, Reconjet, Epson Moverio, Sony, ODG, etc.).

VR appeared on the graph in 2014, the year Oculus was bought by Facebook for \$3B and coincided with the first large round of investment by Magic Leap Corp. (\$1/2B by Google and Qualcomm), which was followed by many similar rounds (a round E continues this trend today, 7 years after its creation and 2 years after its first product

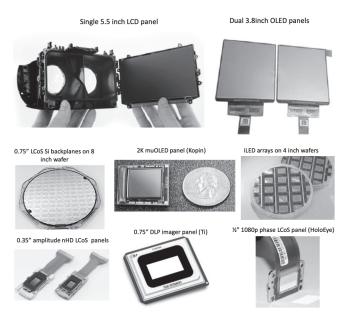


Figure 7.4 Various display panels used in AR/VR products today.

Polarization and emission cone are also important features of any micro-display-panel system (emissive or non-emissive), as they can considerably affect both the brightness of the immersive image at the eye as well as the perceived eyebox size. For example, LCoS-based and LC-based phase panels are polarized display panels (and thus require single polarized illumination), whereas LED (mini-LED or microiLED), mu-OLED or DLP panels and MEMS scanners are unpolarized displays and can therefore use all illumination polarization states. Using a single polarization state (linear or circular) does not necessarily mean reducing the illumination brightness by a factor of 2×, since polarization recovery schemes can be quite efficient and convert 20-30% of the wrong polarization, bringing it up to 70–80% (especially in illumination architectures used free-space in pico-projector illumination engines). Figure 7.4 shows some of these panels used in many AR/VR products today.

Finally, the efficiency of micro-display panels is paramount when it comes to wearable displays. Color-sequential LCoS displays are nearly 50% efficient, whereas color-filter LCoS displays are only about 15% efficient, and LTPS LCD micro-display panels (Kopin) are

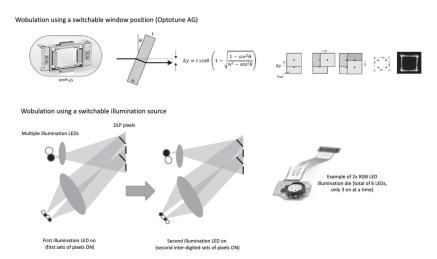


Figure 7.5 Optical wobulation using mechanical movement or multiple illumination.

While mechanical moving and steerable wobulation can act on any display type (provided their refresh rate is high enough), illumination switch wobulation is limited to non-emissive displays such as DLP, HTPS, LCD, and LCoS displays.

Optical wobulation can effectively increase the angular resolution (PPD) without increasing the number of pixels in the display panel. This technique is however limited to display architecture that have potential high refresh rates such as DLPs, and fast LCoS displays.

Another very compact wobulation technique would use multiple mirror pointing angles in a single DLP array, but that considerably increases the difficulty in designing and fabricating the MEMS DLP array. It would yield the most compact optical wobulation architecture.

Optical foveation and optical wobulation both can synthetically increase the number of pixels to yield a high-resolution perception for the viewer without increasing the physical number of pixels in the display. However, optical wobulation is not necessarily a form of optical foveation. It can morph into an optical foveation architecture if the wobulation is gaze contingent and can be steered by fractions of pixels over larger parts of the immersive FOV (see also the wobulation section on LBS display architectures).

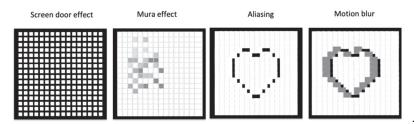


Figure 7.6 Screen-door effect, Mura effect, motion blur, and display aliasing.

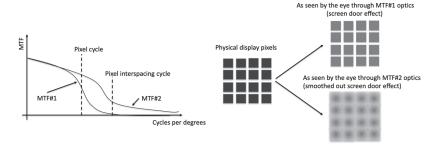


Figure 7.7 Tuning the MTF of the optics to smooth out the screen-door effect.

Other parasitic display effects from direct-view or micro-display panels are crepuscular rays. Crepuscular rays are streaks of light that can come from various sources, such as diffusion, diffraction, or even Fresnel lens rings. In a VR system, they can be prominent due to bright white text over a dark field.

The screen-door effect might be reduced by tuning either the MTF of the collimation lens in a VR system or the MTF of the display engine in an AR system (see Fig. 7.7). Although the physical display pixels still show a screen door, as will the virtual image through a high quality lens (MTF#1), an imaging system with a reduced MTF (MTF#2) can smooth out the virtual image in the angular space if the optics cannot resolve the pixel interspacing cycles further.

The human eye, with its impressive visual acuity allowing one to resolve features well below the arcmin scale, can image whatever the display engine can provide, at least with today's limited-pixel-density display technologies. Thus, acting on the display engine's MTF can

backlight in V1 and Kopin's LCD with a backlight in V2) is templemounted and collimated by a 100% reflective metal-coated lens located on the nasal side. The collimated field is then redirected to the user's eye by a 50/50 beam splitter. The use of a PBS to redirect the field into the user's eye would have been much more effective, but the lack of available low-birefringence plastic to make the rod led to the optimal choice of a 50/50 beam splitter, as losing brightness is a better option than producing ghost images from unwanted polarization states.

11.5 See-Around Prim Combiners

Another declination of the lateral linear lightguide combiner for small-FOV "see-around" smart glasses is shown in Fig. 11.7. These are not see-through combiners, but they are instead opaque. However, as the tip of the lateral lightguide combiner is tapered to a height that is smaller than the human pupil size (typically 3 mm or less), the combiner can be considered as "see-around" for the user, at least in the far-field domain.

As the lightguide combiner is not see-through here, the best adapted architecture might not be the double-pass birdbath Google Glass architecture shown in Fig. 11.5 but rather a more efficient single-pass version based on a prism ending and a collimation lens at the exit surface of the lightguide (see combiner tip with prism and lens in Fig. 11.6). This yields also a larger eyebox since the collimation lens is closer to the eye. Examples of such see-around smart glasses are the Kopin Solis (designed for cycling sports) or the Olympus smart glasses. The lateral surfaces can be structured (or ribbed) to reduce

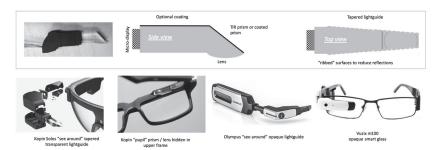


Figure 11.7 Opaque tapered see-around lightguides (left and center) and wider opaque lightguide (right) for small-FOV monocular smart glasses.

18.4 Focus Tuning through Display or Lens Movement

The most straightforward way to change the location of the virtual image in front of the user, especially in a VR system, is to mechanically change the distance between the display panel and the collimation lens. This has been investigated by the computational display group at Stanford University¹⁰⁰ and in the Oculus Half Dome prototype unveiled in 2018 by Facebook Reality Labs (FRL); see Fig. 18.6.

FRL produced another VR varifocal system by using a non-moving optical architecture based on stacked liquid crystal lenses, as presented at the Oculus Connect 6 event in 2019 (see Fig. 18.7).

In the FRL architecture, six stacked LC lenses provide up to 2⁶ (128) different foci to the VR content. This is a smart way to alleviate the downside of LC lenses, which cannot produce enough optical power due to the limited LC birefringence and LC thickness that can be reached. By stacking low-power LC lenses, relatively large LC lens apertures can be used without moving towards the use of Fresnel LC



Figure 18.6 Focus tuning of an entire scheme by moving the display panel to the lens in VR systems.



Figure 18.7 Facebook Reality Labs VR varifocal lens based on stacked LC lenses, and operation example.

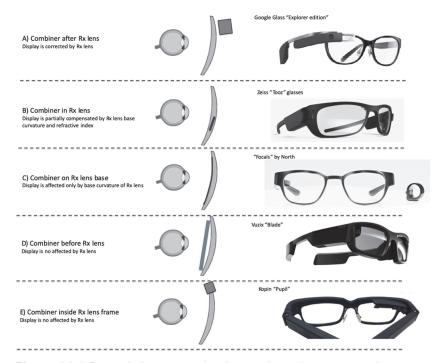


Figure 21.2 Prescription correction lenses in various monocular smart glass architectures available today, and their effect on the digital display.

Figure 21.2 summarizes various prescription (Rx) compensations integration in some of the monocular smart glass architectures available today in industry. Five different cases are depicted in this figure:

- A: combiner after the Rx lens,
- B: combiner inside the Rx lens.
- C: combiner on the base surface of the Rx lens,
- D: combiner before the Rx lens, and
- E: combiner set inside the Rx lens frames.

There is no example of an architecture where the combiner would be located on the outer surface of the Rx lens since this would produce a complex "Mangin mirror" effect that would be difficult to manage optically. In conventional ophthalmic lenses, the base curvature is usually the generic curvature (cast within the ophthalmic puck) while

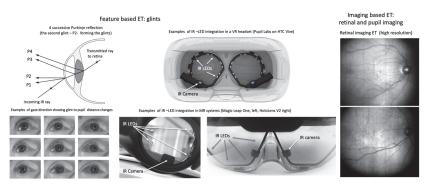


Figure 22.7 Feature- and imaging-based ET techniques and implementation examples.

There are two main ET techniques used today (see Fig. 22.7):

- image-based ET (pupil position, size, and orientation, as well as more complex retinal imaging), and
- feature-based ET (using glints produced by IR LEDs).

Both techniques require IR cameras and some sort of IR lighting (single or multiple LEDs, flood or structured illumination), all in proximity to the eye. Glint-based ET that uses sets of IR LEDs around the combiner, pointing to the eye, are the most popular today (SMI/Apple, EyeFluence, Tobii, Pupil Labs, Magic Leap One, HoloLens V2, etc.). Both image- and feature-based architectures rely on IR illumination (850 nm up to 920 nm, depending on the IR sources used) to be most effective with B&W silicon photodetector arrays and also to be insensitive to display- or world-illumination changes (regardless of intensity and orientation).

Retinal imaging is a well-known pupil pursuit technique that has been used in ophthalmology for decades but very seldom for ET. When retinal scanning is combined with pupil center tracking, the technique can be made insensitive to slippage (movement of the headset due to sweat, shocks, etc.). Glint-based ET techniques are less forgiving for slippage. Retinal scanning can be easily combined with iris recognition. Retinal scanning is also a good technique to investigate diabetes-induced blood-vessel degeneration, glaucoma, and agerelated macular degeneration (AMD).